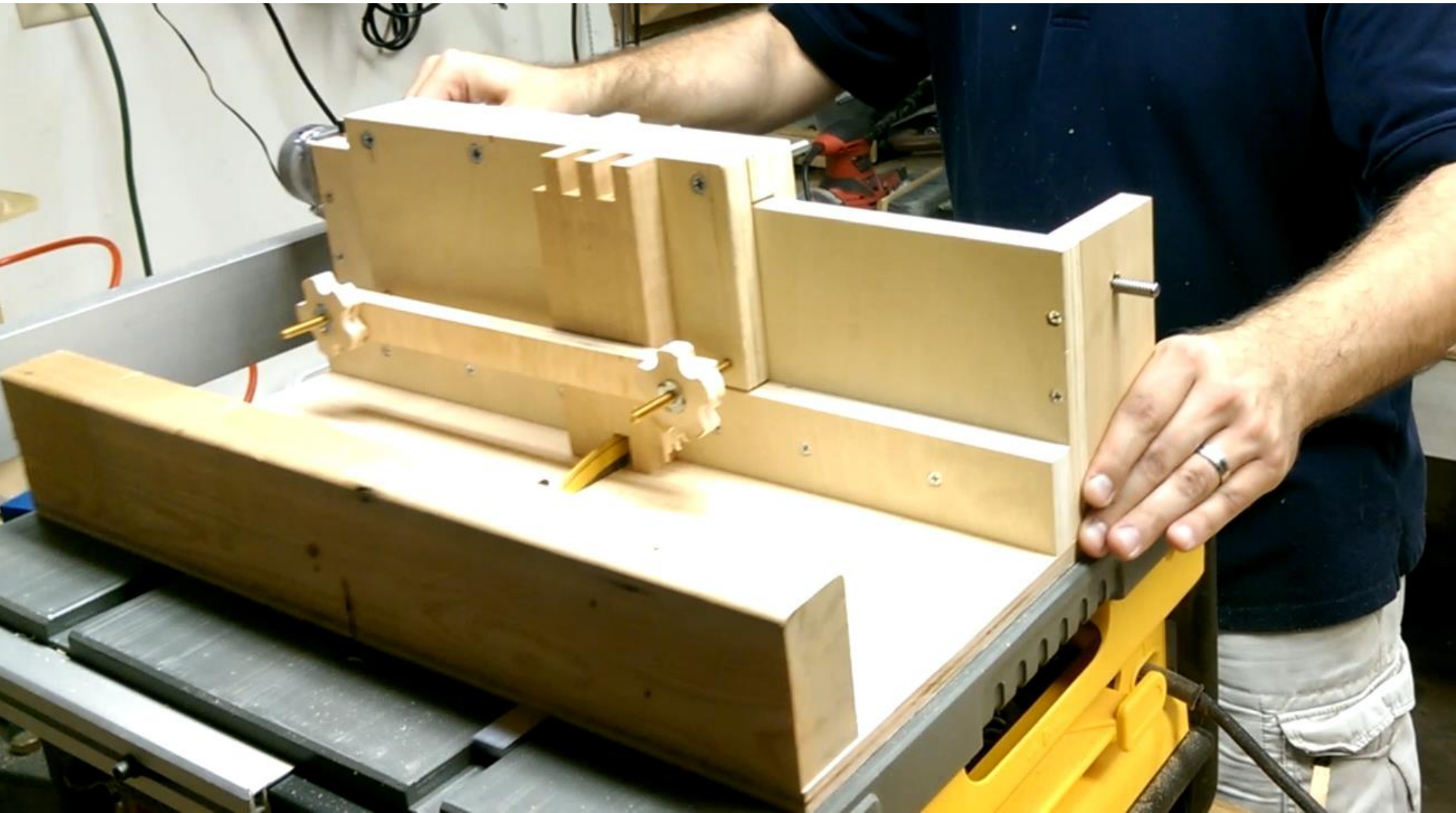


# Running C# on my Table Saw

## Raspberry Pi 3, .NET, and a Web Server



# Ben Brandt



Husband & Father



Manufacturing  
Engineer



Microsoft  
Developer

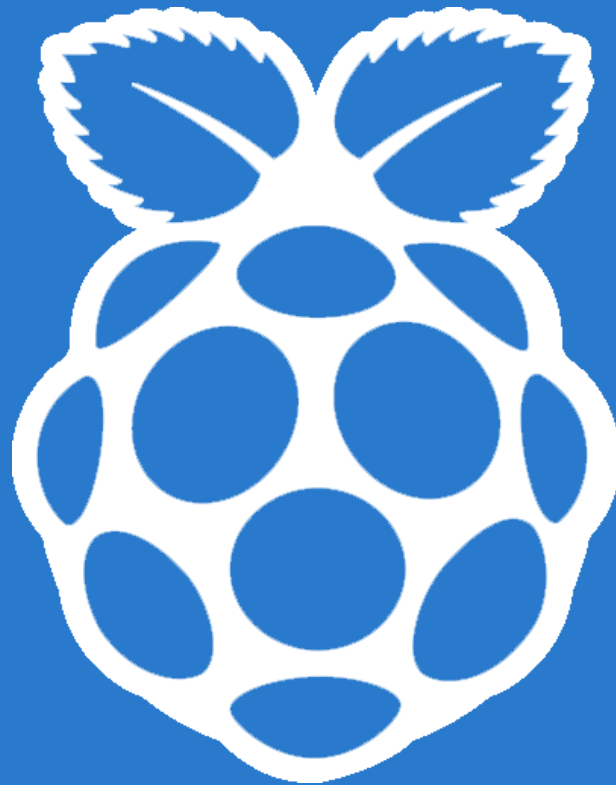


YouTube "Maker"

[www.B2Builds.com](http://www.B2Builds.com)

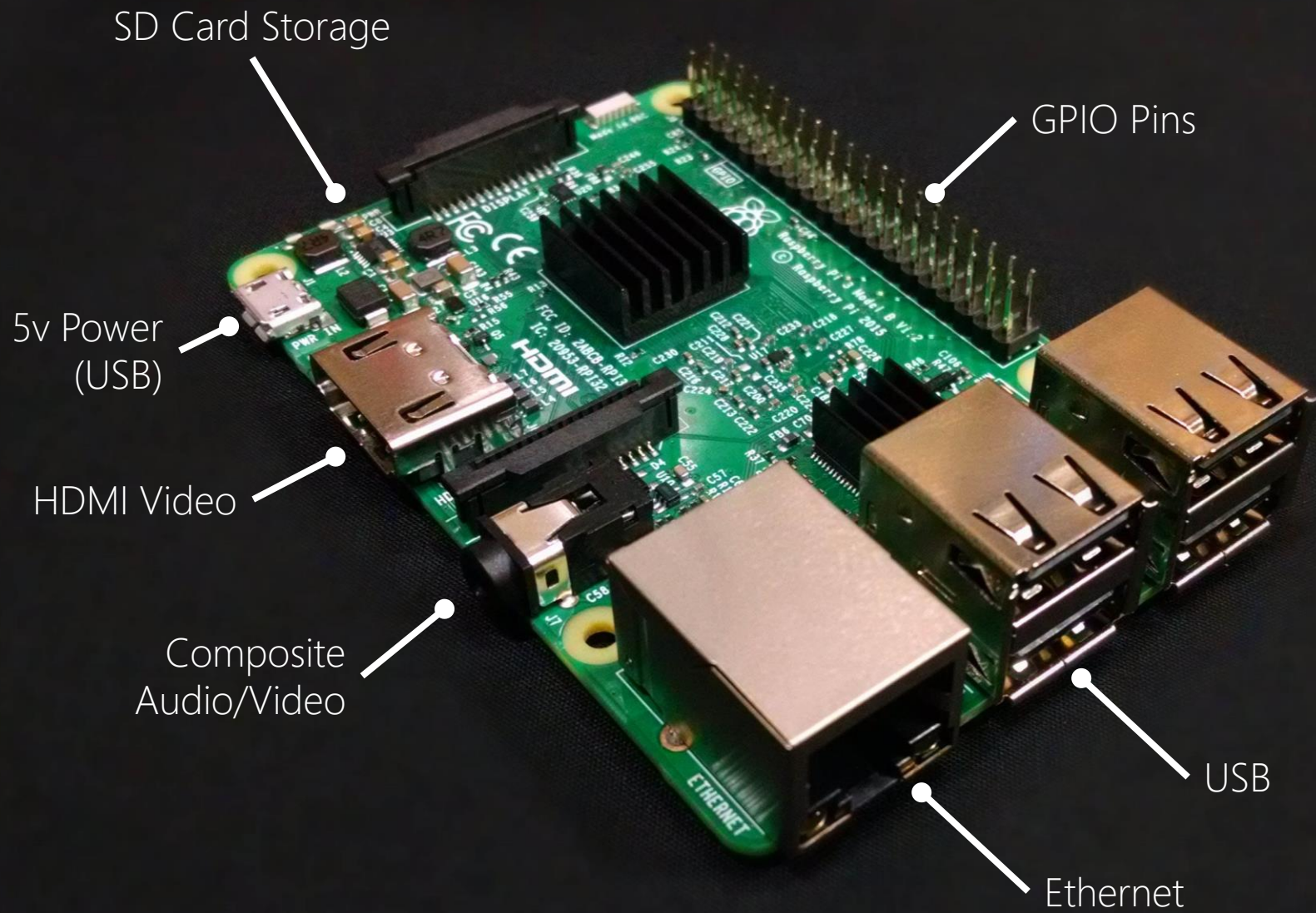


# Raspberry Pi



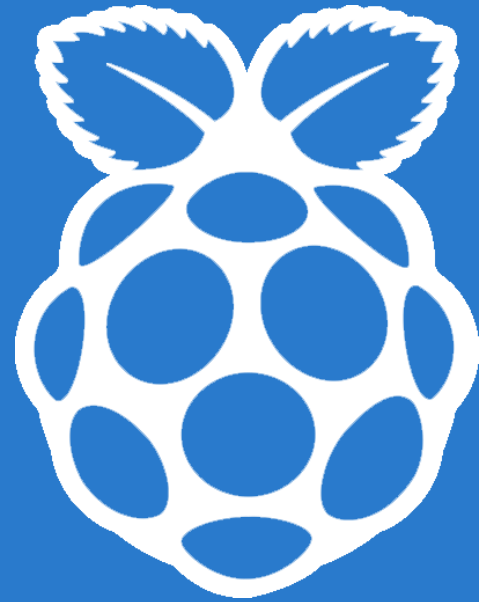
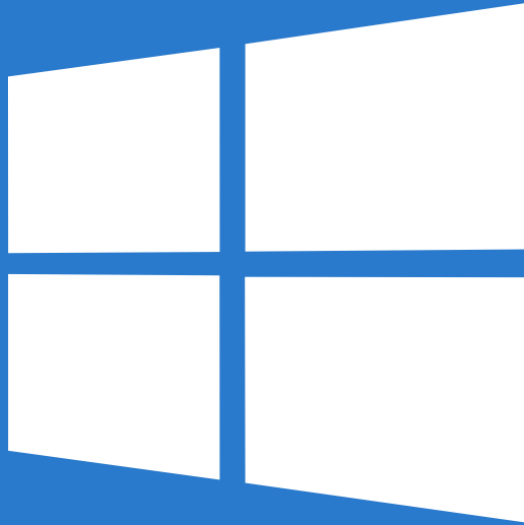








# Windows on Raspberry Pi

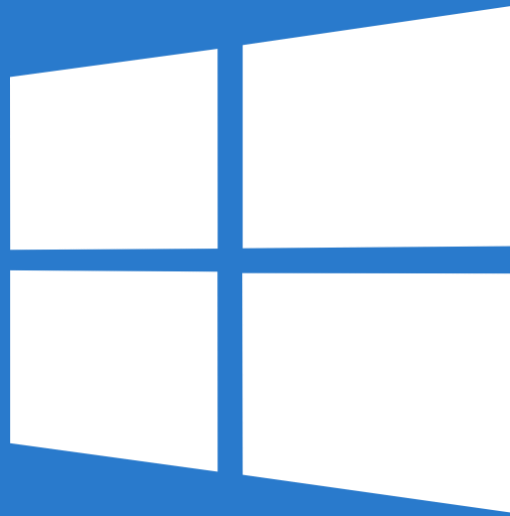








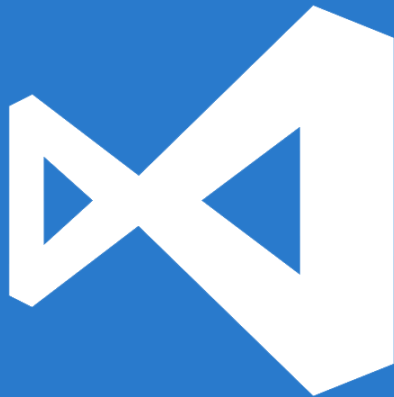
# Windows 10 IoT Core



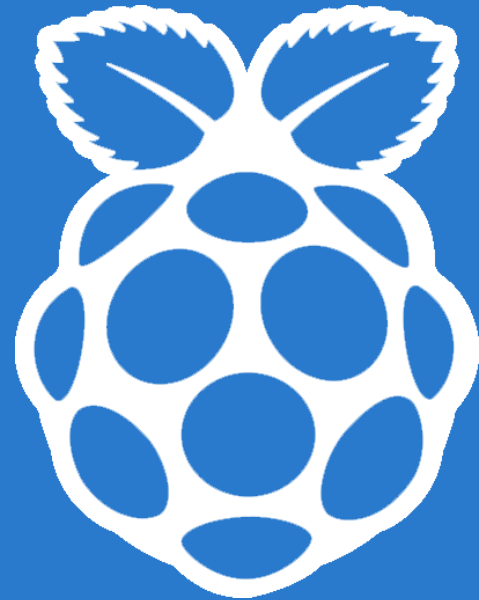
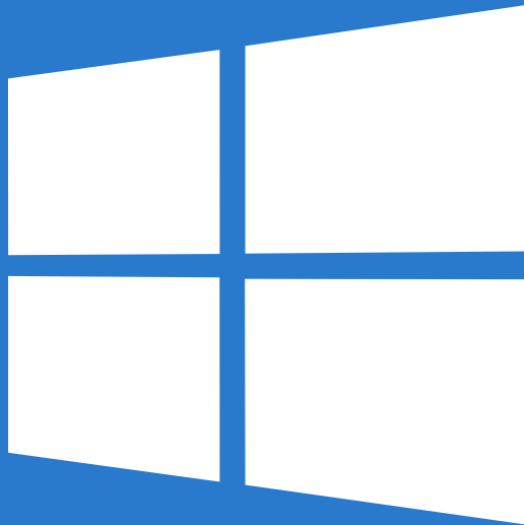
# Windows 10 IoT Core

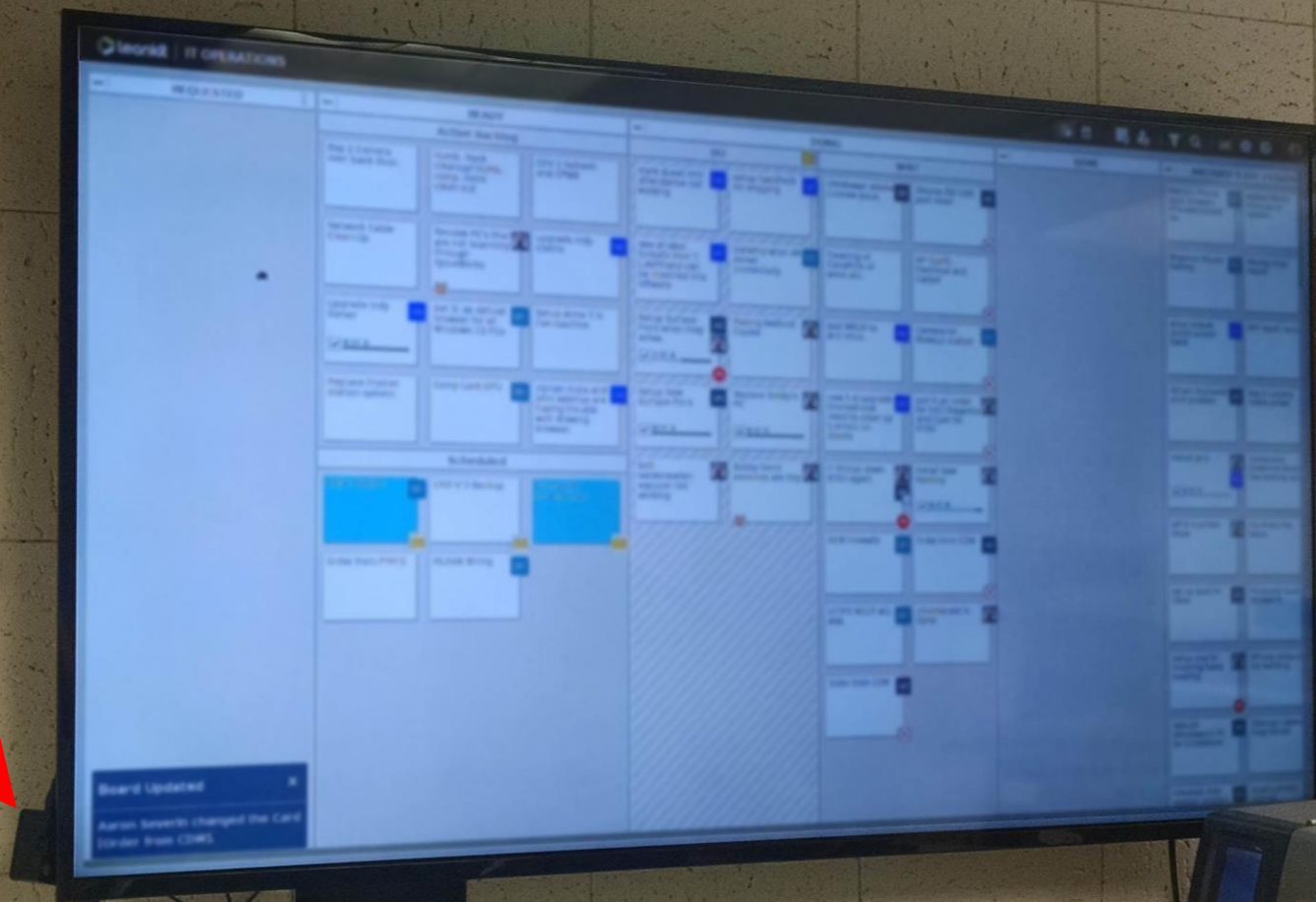
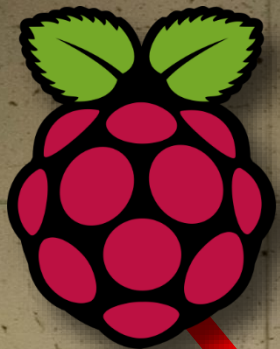
+

Universal Windows Platform (UWP) apps

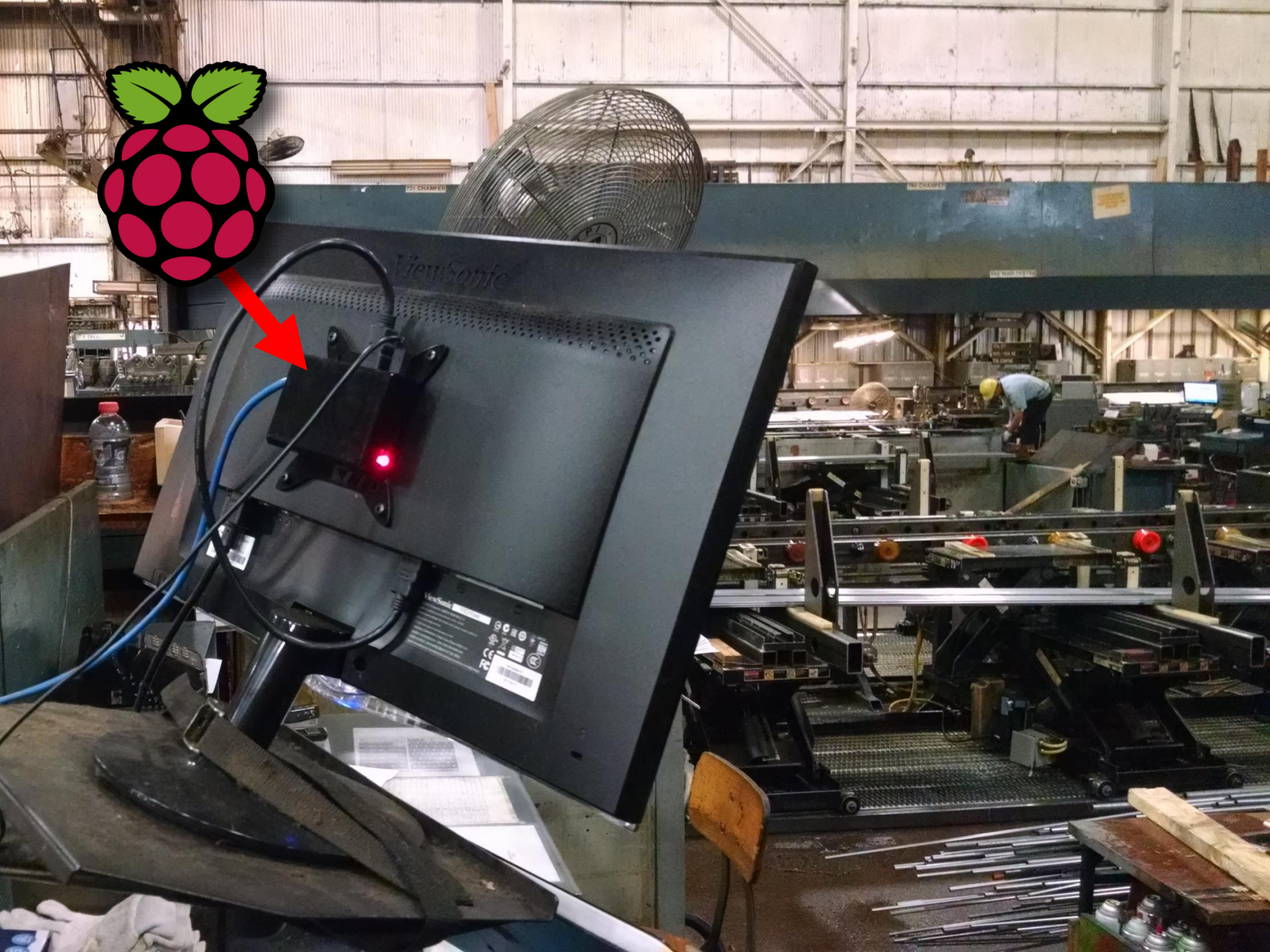
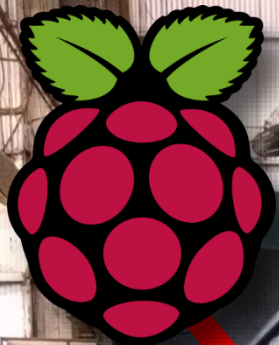


# Business Applications

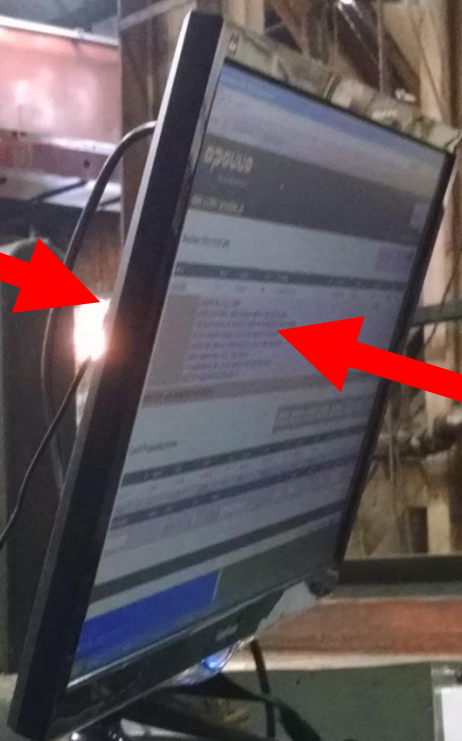
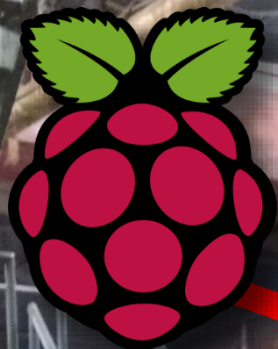




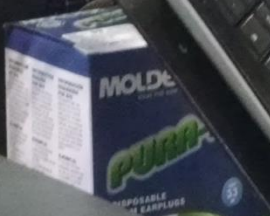








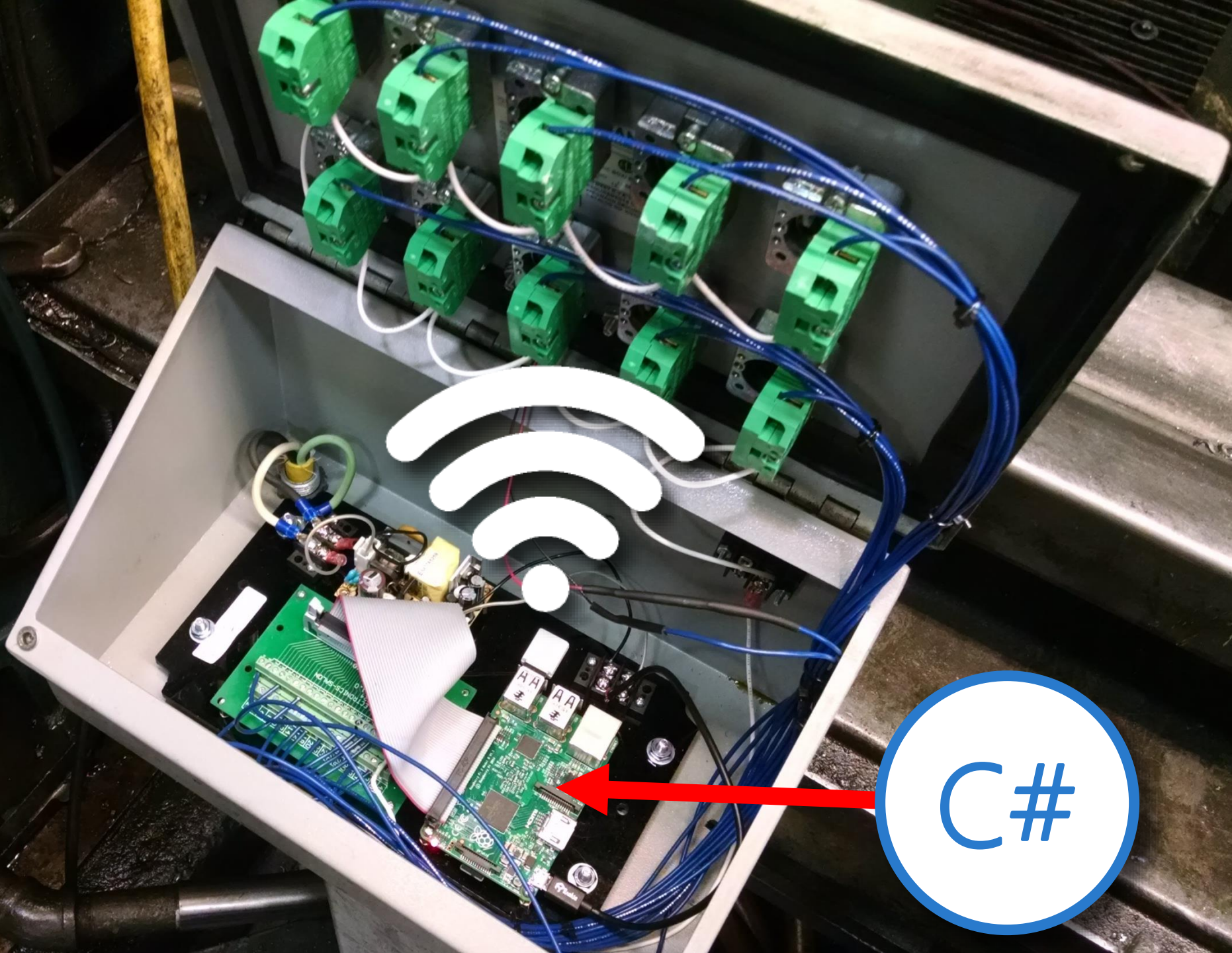
Process Lines % Runtime  
28.3 %  
GOAL  
9.1 %



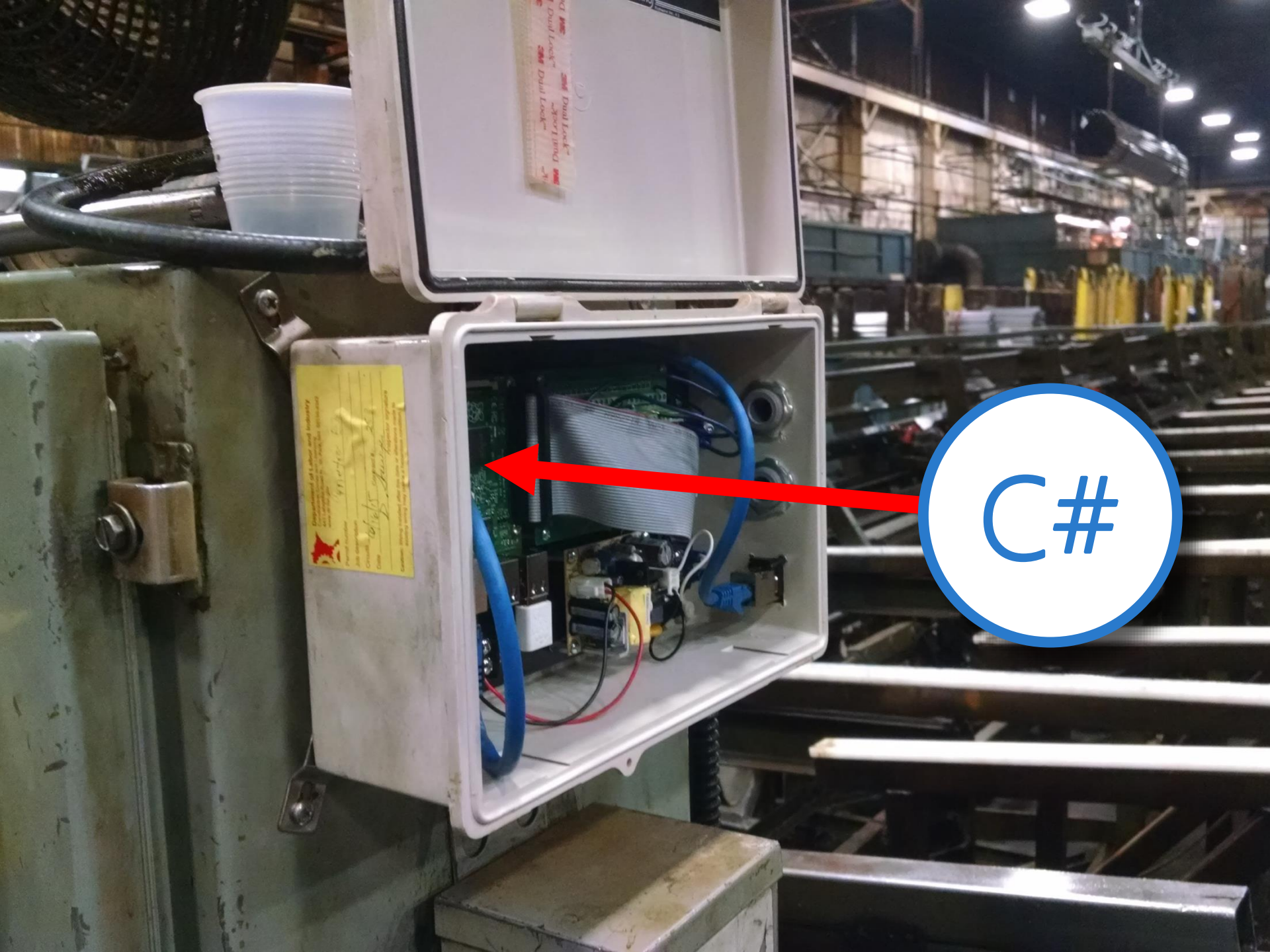








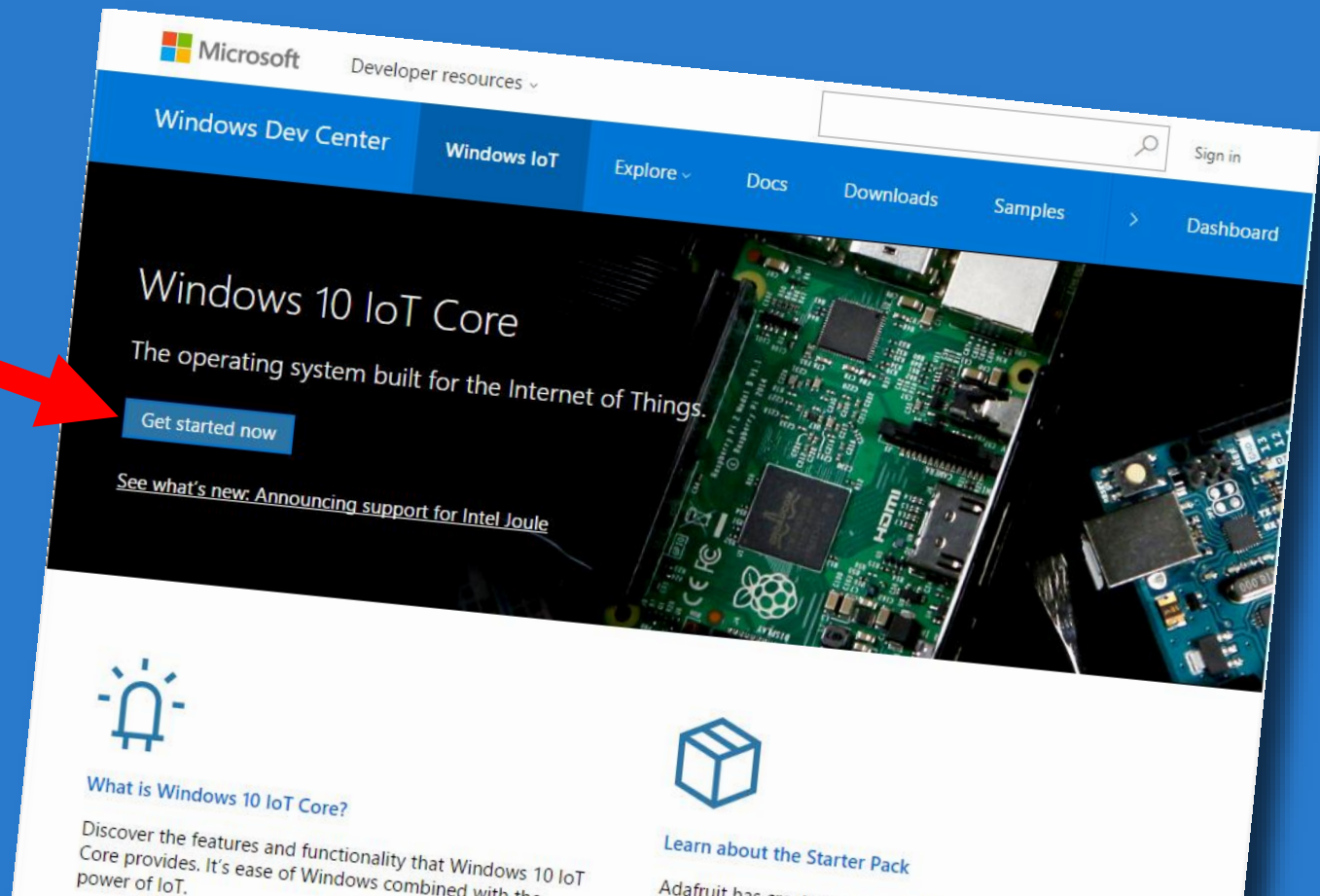




C#

# Raspberry Pi Setup

www.WindowsOnDevices.com



# Development Environment



Windows 10

+



Visual Studio

Community 2015



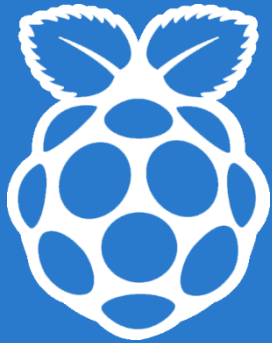






C#

# Building a Box Joint Jig



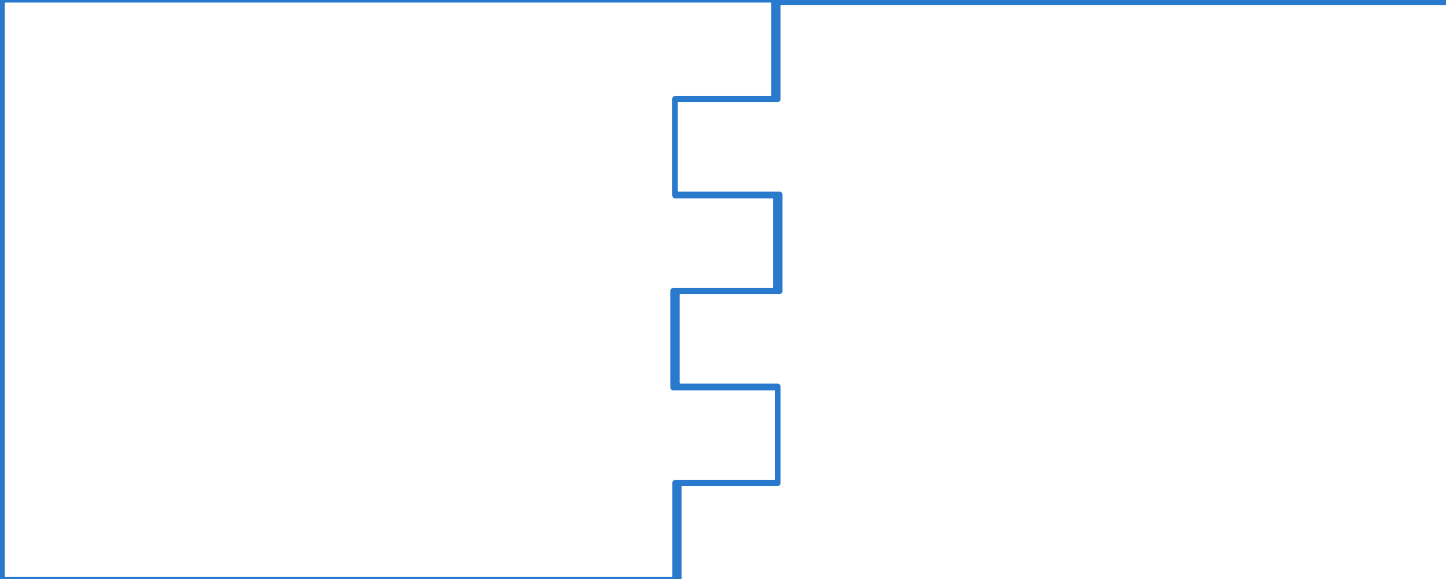
+



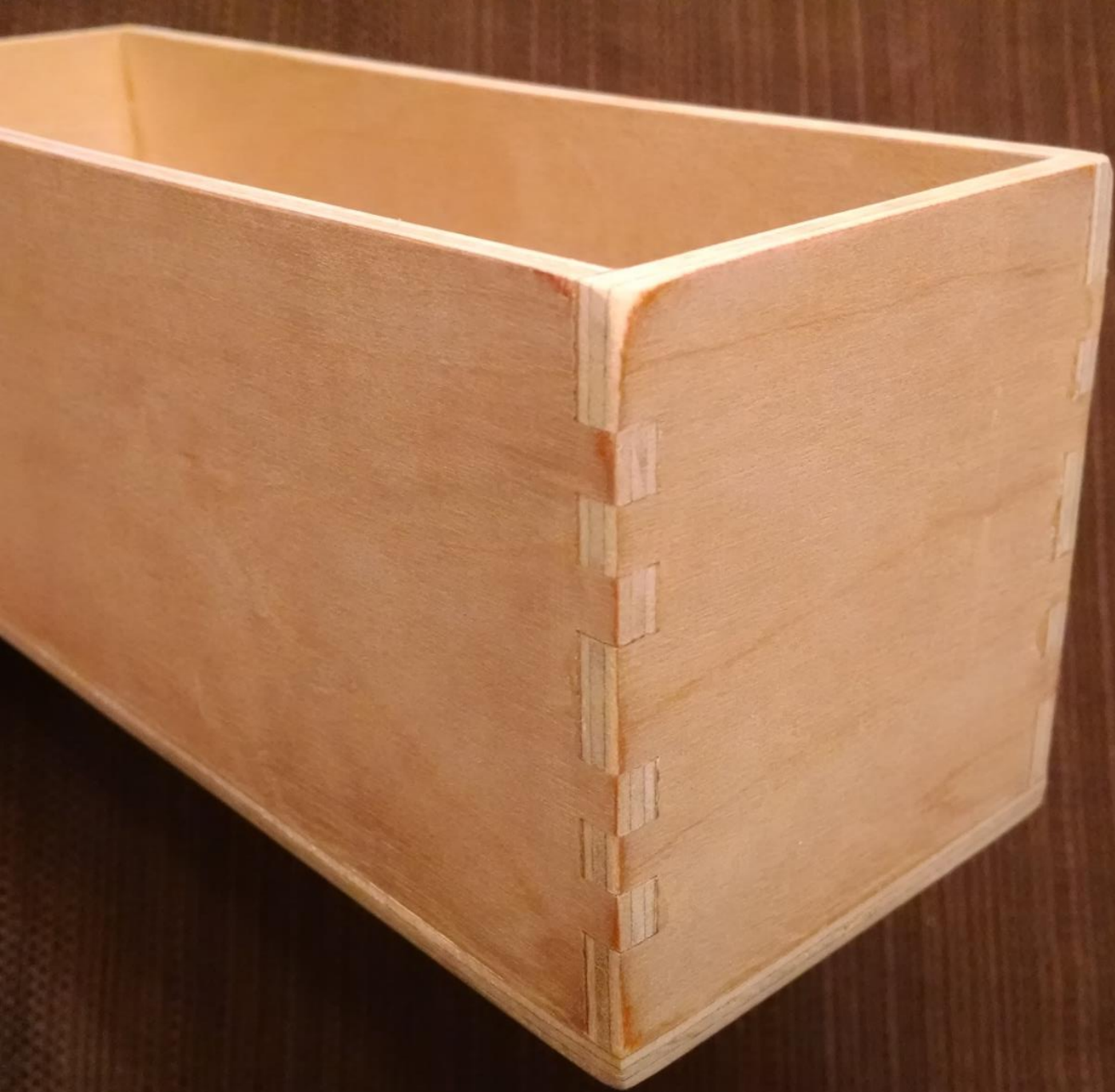
+



# Box Joint





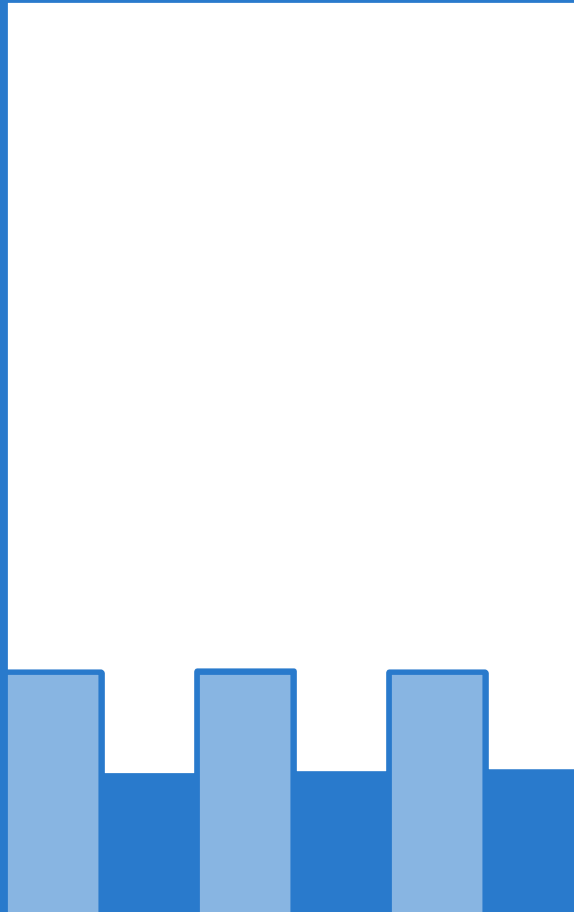






# Cutting Box Joints

Usually cut with a wide (“dado”) saw blade



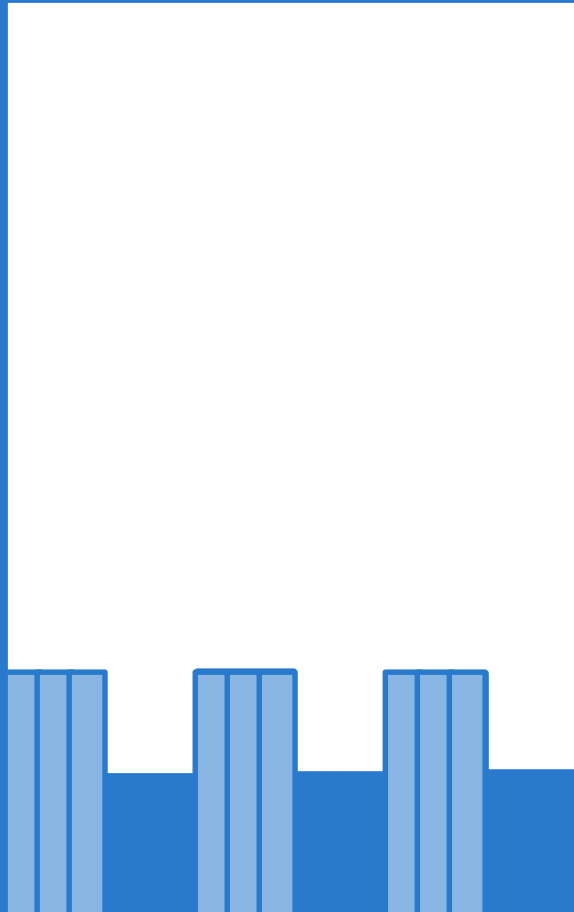
# My Table Saw



\* only supports a normal narrow blade

# Cutting Box Joints

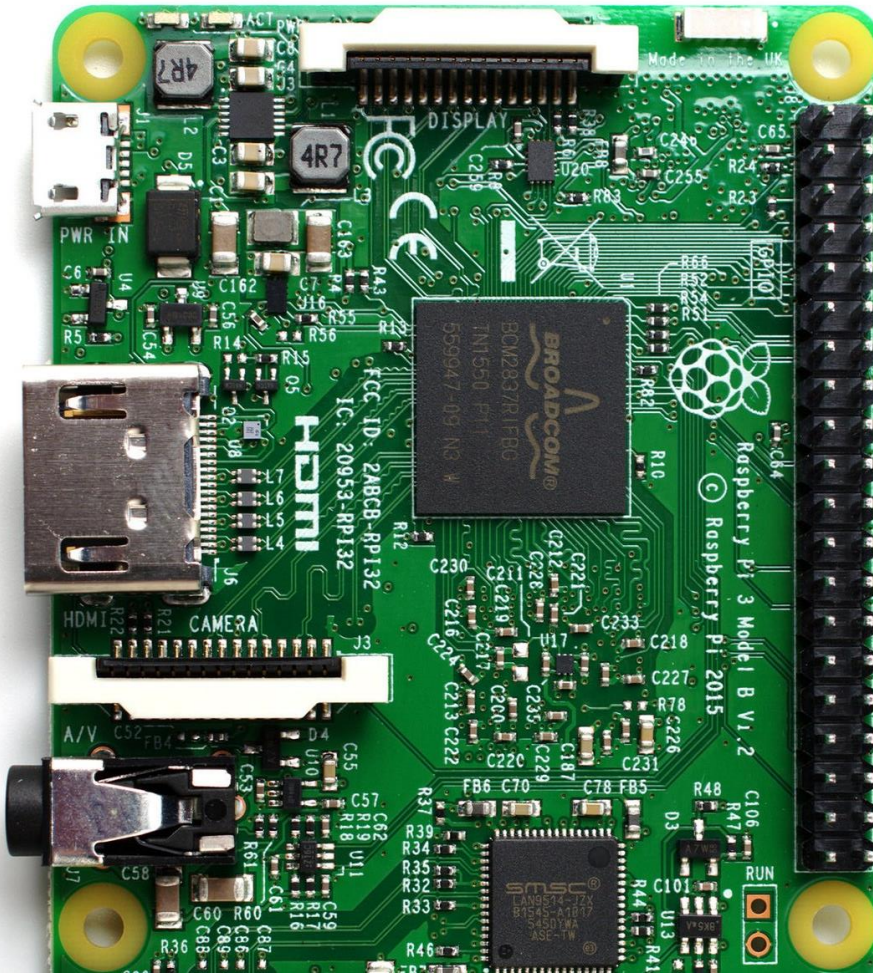
Normal blade requires many precision cuts





# GPIO

General purpose Input & Output



# GPIO

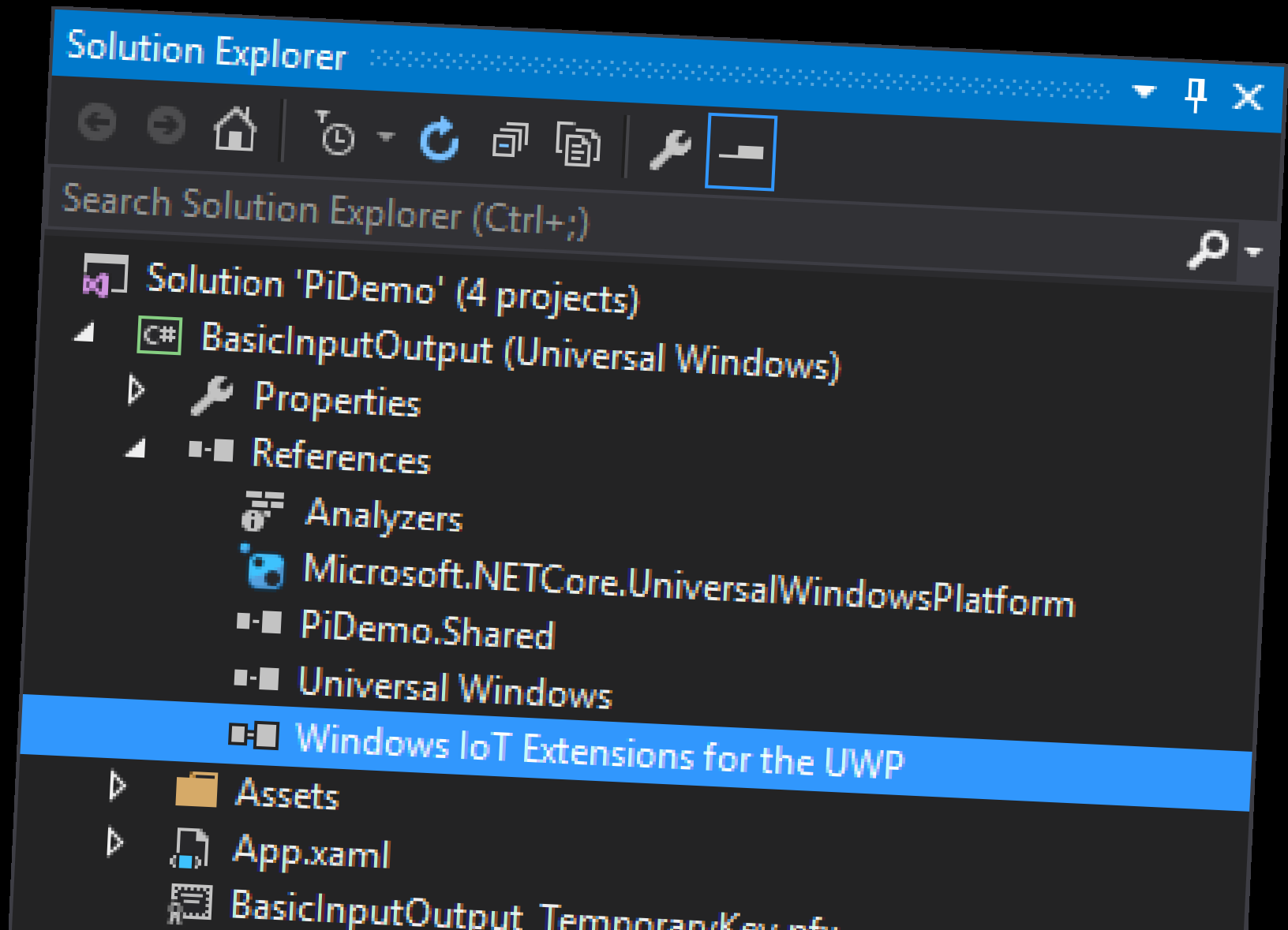
## General purpose Input & Output

Raspberry Pi 3 GPIO Header					
Pin#	NAME		NAME	Pin#	
01	3.3v DC Power	Red	DC Power 5v	02	Red
03	GPIO02 (SDA1 , I <sup>2</sup> C)	Blue	DC Power 5v	04	Red
05	GPIO03 (SCL1 , I <sup>2</sup> C)	Blue	Ground	06	Black
07	GPIO04 (GPIO_GCLK)	Green	(TXD0) GPIO14	08	Orange
09	Ground	Black	(RXD0) GPIO15	10	Orange
11	GPIO17 (GPIO_GEN0)	Green	(GPIO_GEN1) GPIO18	12	Green
13	GPIO27 (GPIO_GEN2)	Green	Ground	14	Black
15	GPIO22 (GPIO_GEN3)	Green	(GPIO_GEN4) GPIO23	16	Green
17	3.3v DC Power	Red	(GPIO_GEN5) GPIO24	18	Green
19	GPIO10 (SPI_MOSI)	Purple	Ground	20	Black
21	GPIO09 (SPI_MISO)	Purple	(GPIO_GEN6) GPIO25	22	Green
23	GPIO11 (SPI_CLK)	Purple	(SPI_CE0_N) GPIO08	24	Purple
25	Ground	Black	(SPI_CE1_N) GPIO07	26	Purple
27	ID_SD (I <sup>2</sup> C ID EEPROM)	Yellow	(I <sup>2</sup> C ID EEPROM) ID_SC	28	Yellow
29	GPIO05	Green	Ground	30	Black
31	GPIO06	Green	GPIO12	32	Green
33	GPIO13	Green	Ground	34	Black
35	GPIO19	Green	GPIO16	36	Green
37	GPIO26	Green	GPIO20	38	Green
39	Ground	Black	GPIO21	40	Green

Rev. 2  
29/02/2016

[www.element14.com/RaspberryPi](http://www.element14.com/RaspberryPi)

# Accessing GPIO From Code



# Initializing Pins

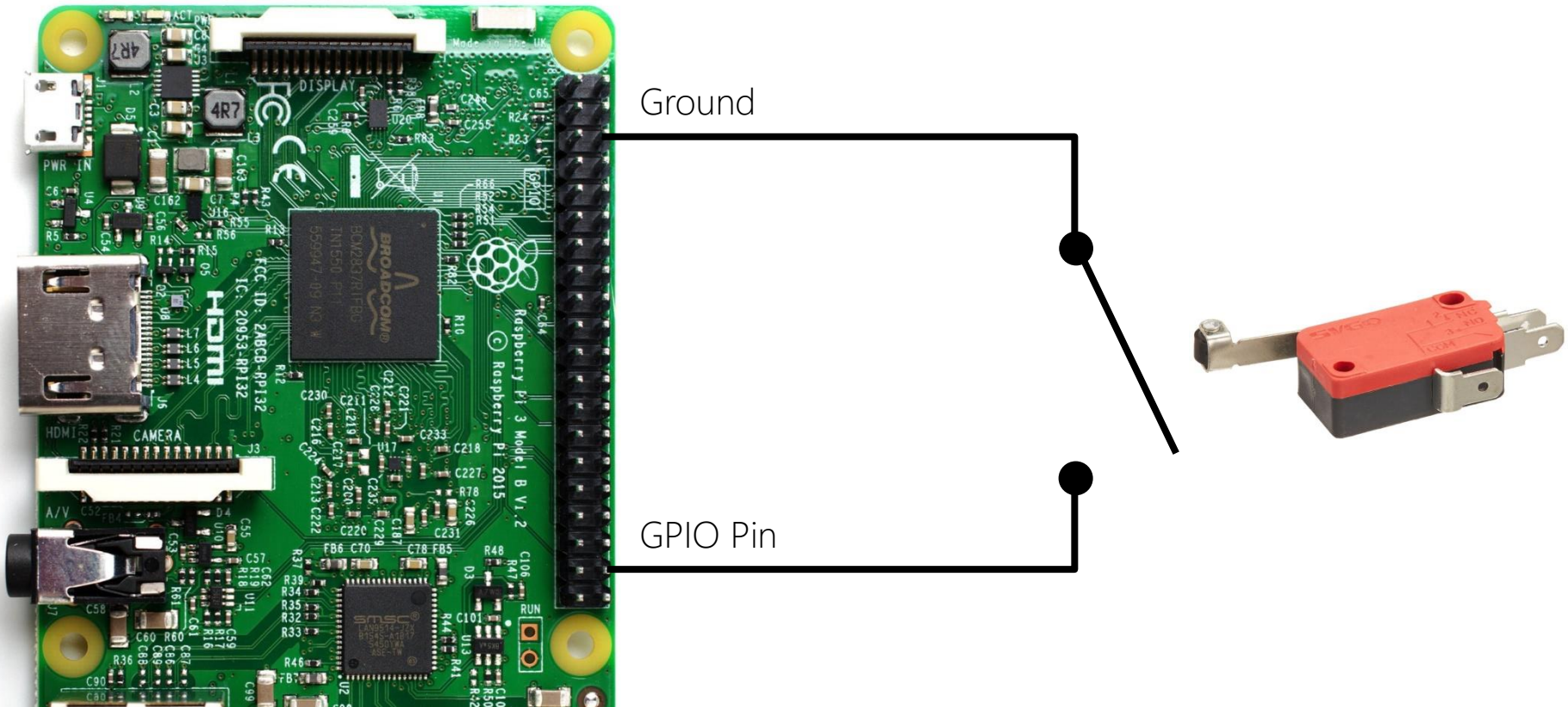
`Windows.Devices.Gpio.GpioPin`

- Set up your pins once
- Keep your pin variables referenced



# GPIO

## Input



# Initializing Pins: Input

```
public static GpioPin InitializeInput(int gpioPinNumber)
{
    var gpioController = GpioController.GetDefault();

    var gpioPin = gpioController.OpenPin(gpioPinNumber);
    gpioPin.SetDriveMode(GpioPinDriveMode.InputPullUp);
    gpioPin.DebounceTimeout = TimeSpan.FromMilliseconds(50);
    return gpioPin;
}
```

# Initializing Pins: Input

```
public static GpioPin InitializeInput(int gpioPinNumber)
{
    var gpioController = GpioController.GetDefault();

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    gpioPin.DebounceTimeout = TimeSpan.FromMilliseconds(50);
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}
```

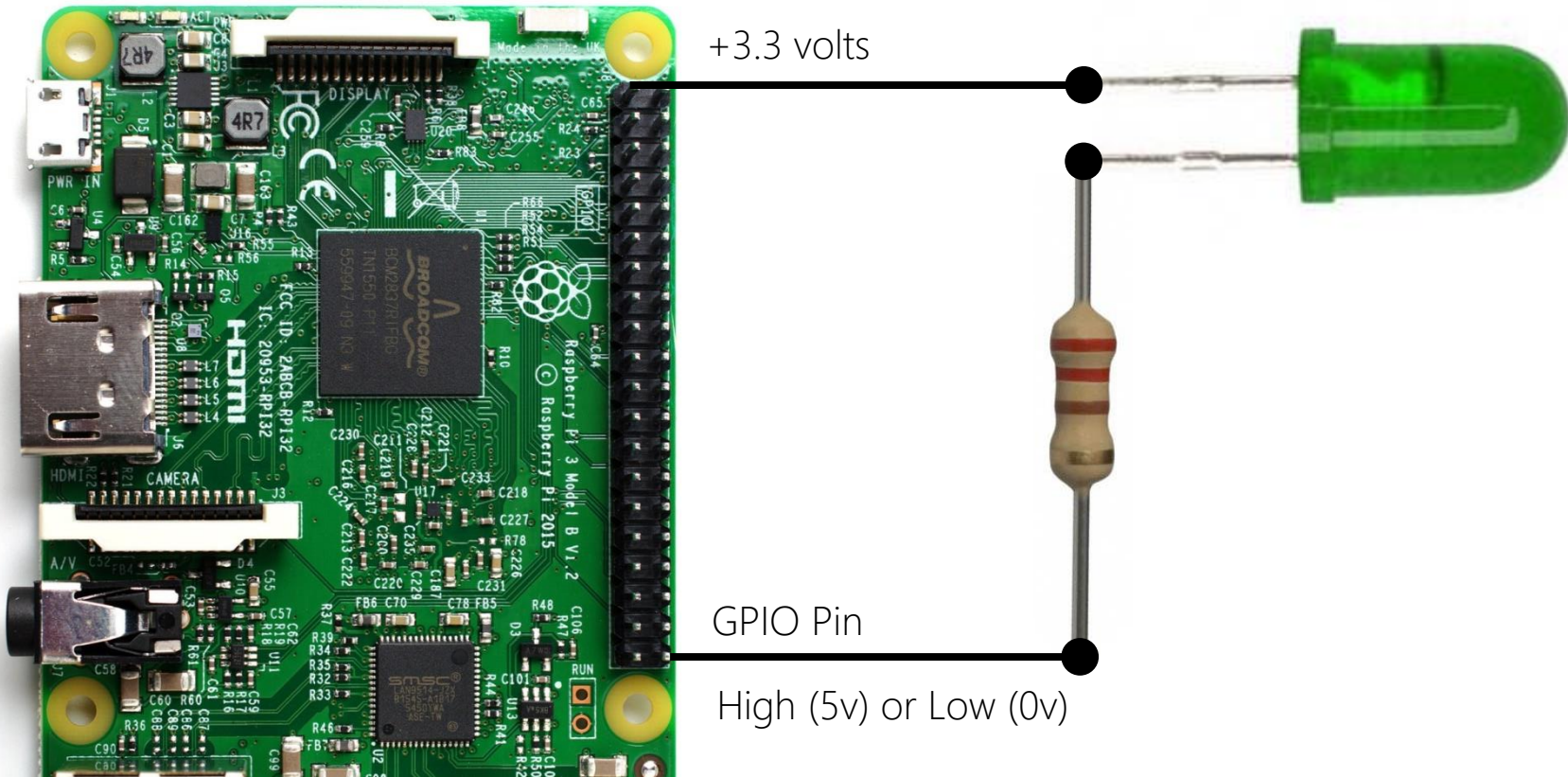
# Initializing Pins: Input

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public static GpioPin InitializeInput(int gpioPinNumber)
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    gpioPin.DebounceTimeout = TimeSpan.FromMilliseconds(50);
    return gpioPin;
}
```

# GPIO

## Output





# Initializing Pins: Output

```
public static GpioPin InitializeOutput(int gpioPinNumber)
{
    var gpioController = GpioController.GetDefault();

    var gpioPin = gpioController.OpenPin(gpioPinNumber);
    gpioPin.SetDriveMode(GpioPinDriveMode.Output);
    return gpioPin;
}
```

# Initializing Pins: Output

```
public static GpioPin InitializeOutput(int gpioPinNumber)
{
    var gpioController = GpioController.Default;

    var gpioPin = gpioController.OpenPin(gpioPinNumber);
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    return gpioPin;
}
```



# Initializing Pins: Output

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public static GpioPin InitializeOutput(int gpioPinNumber)
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    var gpioPin = gpioController.OpenPin(gpioPinNumber);
    gpioPin.SetDriveMode(GpioPinDriveMode.Output);
    return gpioPin;
}
```

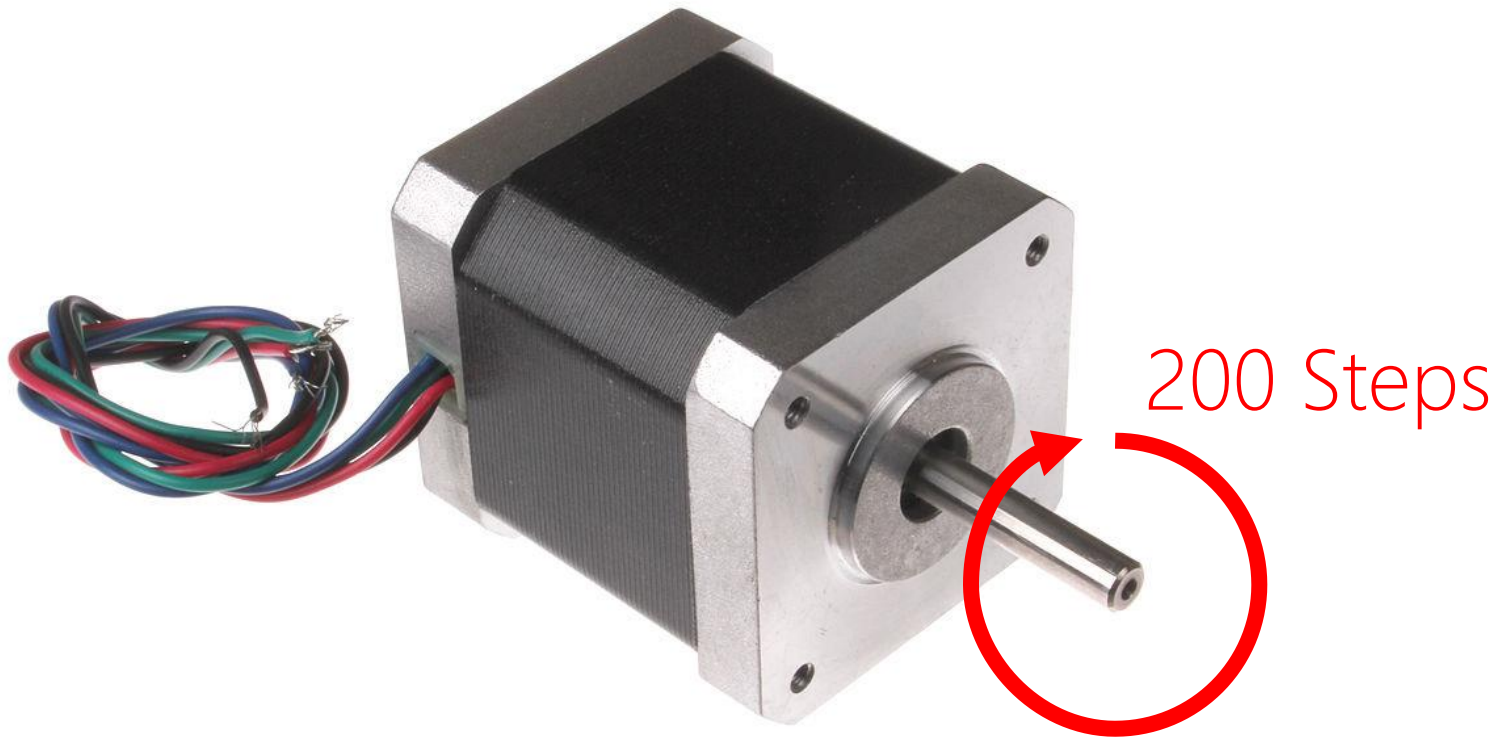
# Motion Control

Lead Screw



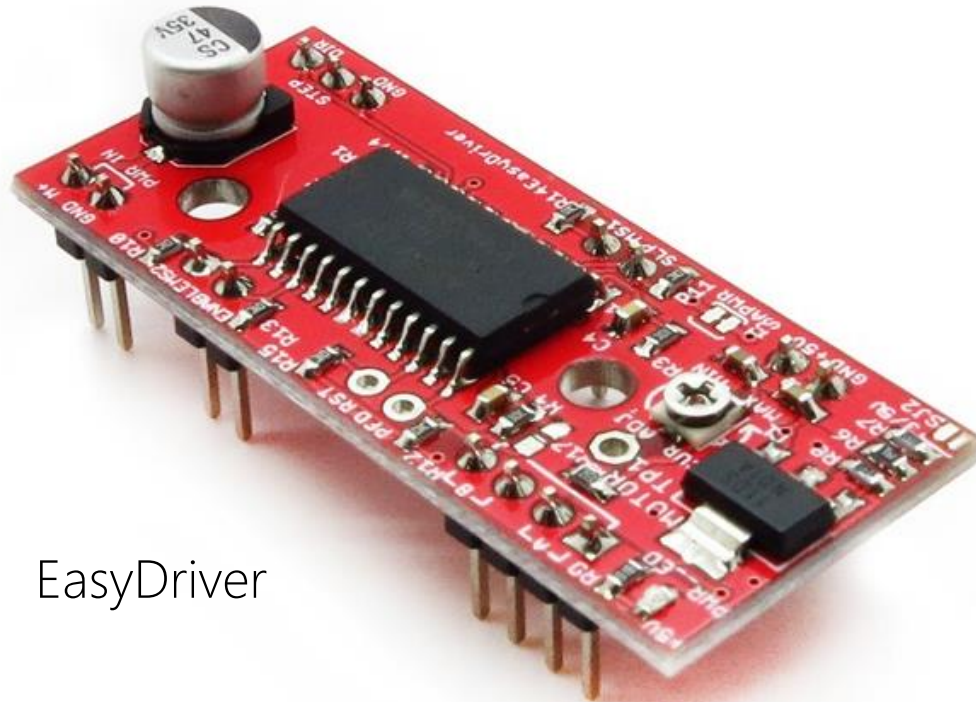
# Motion Control

## Stepper Motor



# Motion Control

## Stepper Motor Driver

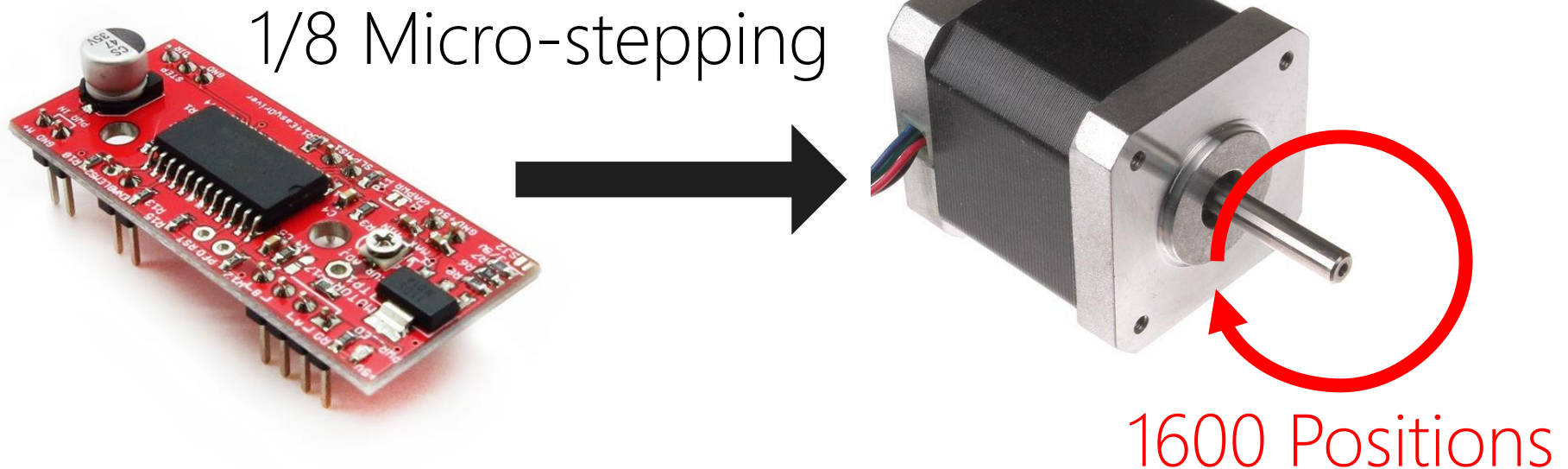


EasyDriver



# Motion Control

## Stepper Motor Driver



# Stepping the Motor

```
for (int i = 0; i < steps; i++)  
{  
    stepPin.Write(GpioPinValue.High);  
  
    await Task.Delay(1);  
  
    stepPin.Write(GpioPinValue.Low);  
}
```

# Stepping the Motor

```
for (int i = 0; i < steps; i++)  
{  
    stepPin.Write(GpioPinValue.High);  
  
    await Task.Delay(1);  
  
    stepPin.Write(GpioPinValue.Low);  
}
```

# Stepping the Motor

**1600 steps**

```
for (int i = 0; i < steps; i++)
```

```
{
```

```
    stepPin.Write(GpioPinValue.High);
```

```
    await Task.Delay(1);
```

**x 1 millisecond each**

```
    stepPin.Write(GpioPinValue.Low);
```

```
}
```

~~**= 1.6 seconds**~~

**25 seconds ?**



# Stepping the Motor

```
for (int i = 0; i < steps; i++)  
{  
    stepPin.Write(GpioPinValue.High);  
  
    await Task.Delay(1);  
  
    stepPin.Write(GpioPinValue.Low);  
}
```

**Async adds  
15ms!**



# Stepping the Motor

```
var sw = new System.Diagnostics.Stopwatch();
```

```
for (int i = 0; i < steps; i++)  
{  
    stepPin.Write(GpioPinValue.High);  
  
    sw.Start();  
    while (sw.Elapsed.TotalMilliseconds < 1) { }  
    sw.Reset();  
  
    stepPin.Write(GpioPinValue.Low);  
}
```

# User Interface

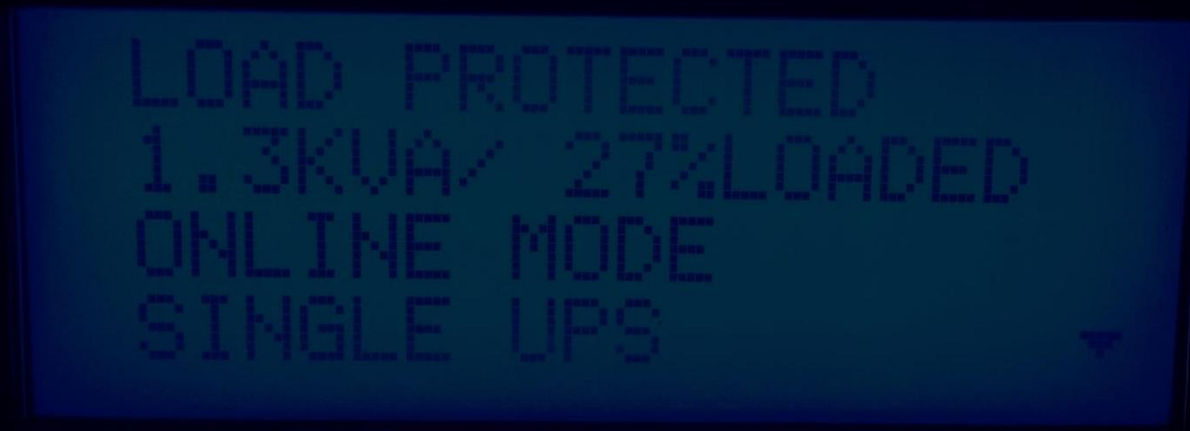
LCD Screen and Buttons?



# User Interface

LCD Screen and Buttons?

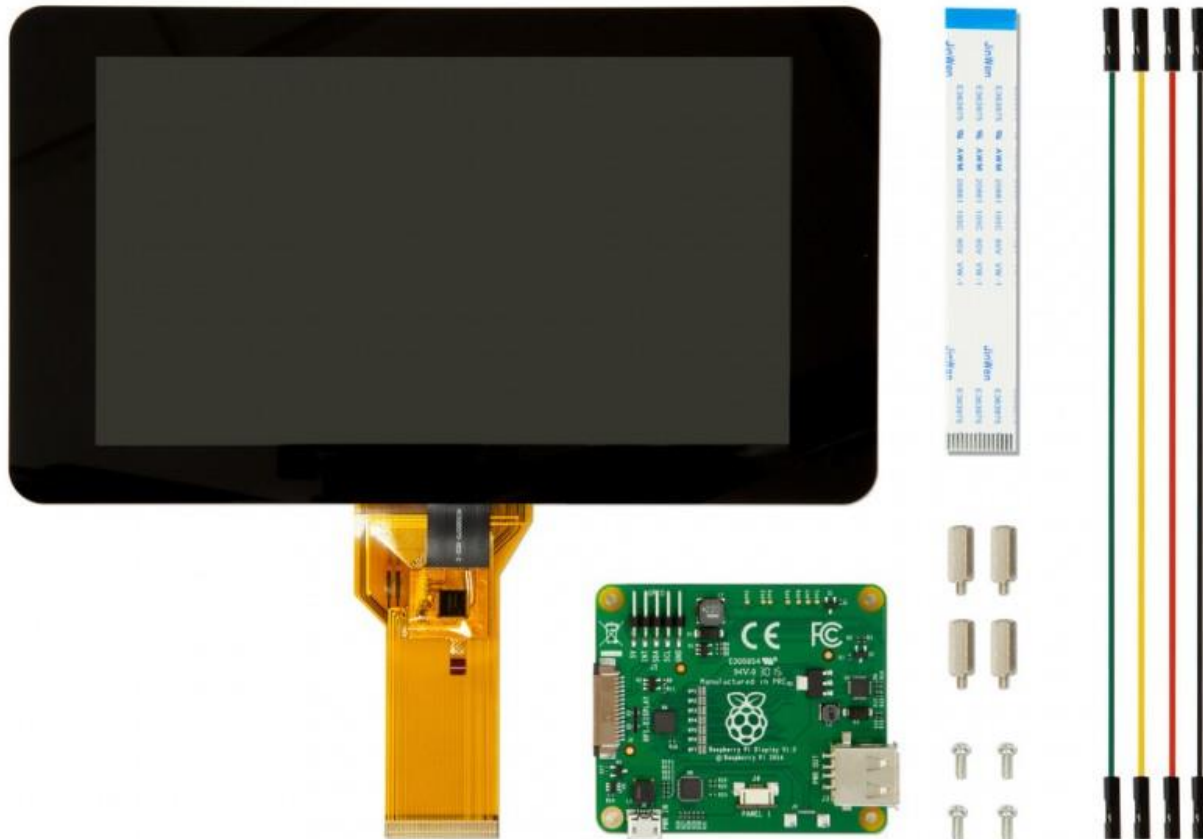
- Adds complexity to hardware & software
  - Limited user experience





# User Interface

Touch Screen?



# User Interface

Touch Screen?

- Adds cost and complexity
- Not ideal for all situations



# User Interface

Why not web based?




# C# Web Server in UWP

?



# C# Web Server in UWP





Build our own  
web server?

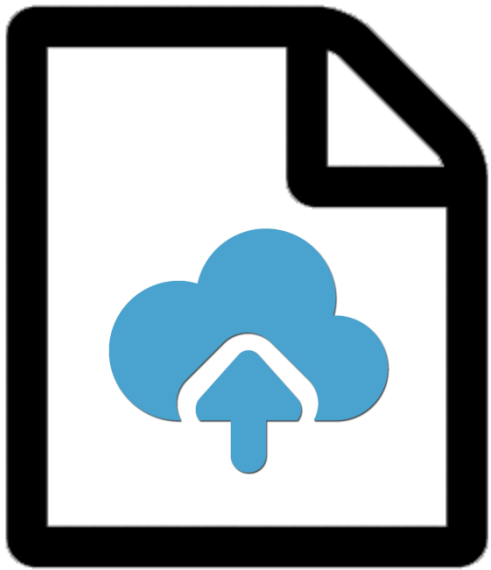
# Restup



Open source .Net Web Server for UWP

[www.nuget.org/packages/Restup](http://www.nuget.org/packages/Restup)

# Restup

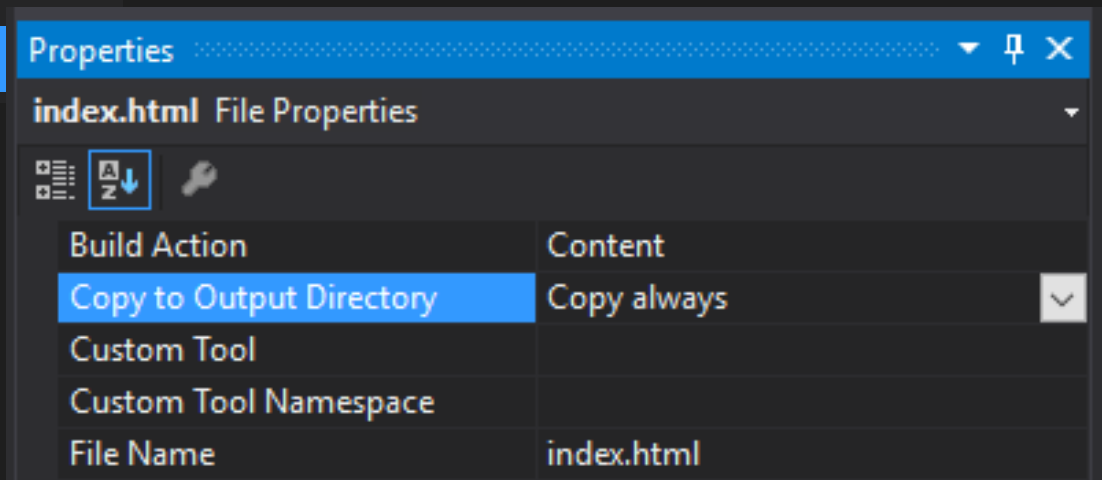
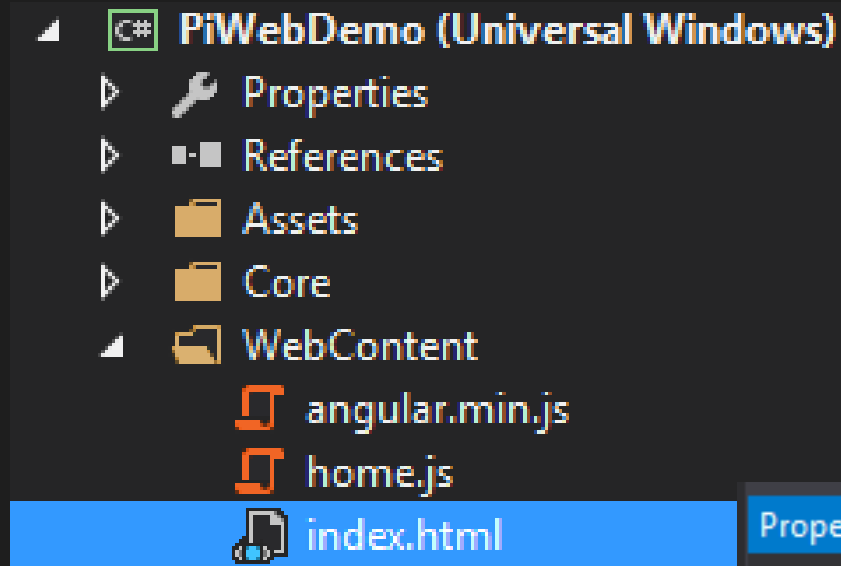


Static files



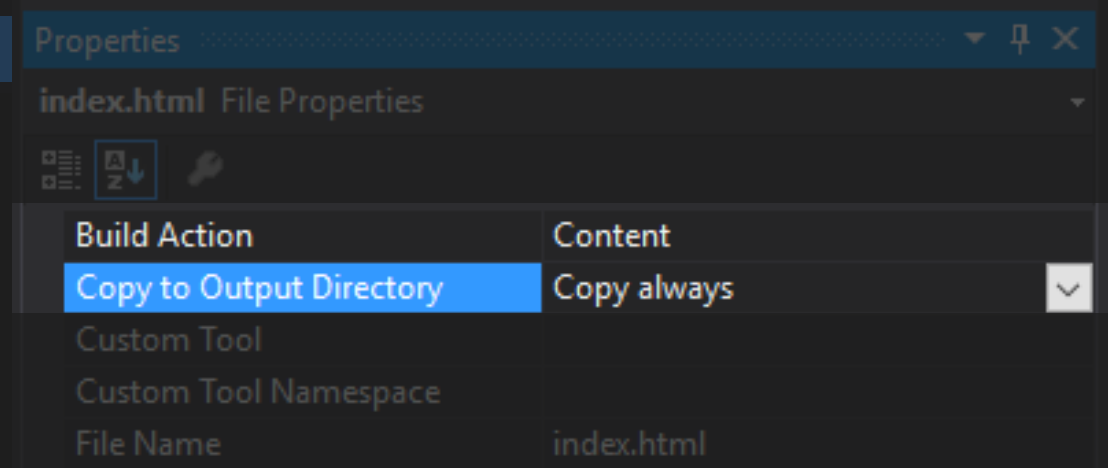
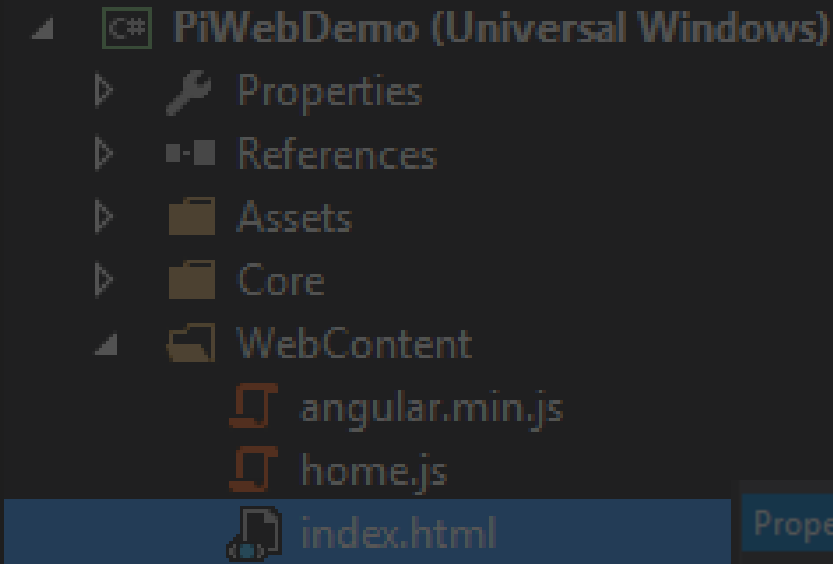
JSON data

# Serving Static Files





# Serving Static Files



D

E

M

O

Box Joint Jig & Code



# Thank You



Ben Brandt

[www.\*\*B2Builds\*\*.com](http://www.B2Builds.com)

[github.com/benbrandt22](https://github.com/benbrandt22)